



AMAGOLD:

Amortized Metropolis Adjustment for Efficient Stochastic Gradient MCMC

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Setting the scene

Markov chain Monte Carlo (MCMC)

Stochastic gradient MCMC (SG-MCMC)

Metropolis-Hastings (M-H) correction

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Are a family of sampling methods popular in Bayesian inference

Approximate computationally intractable posterior

Depend on size of inference task's dataset

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Stochastic gradient MCMC (SG-MCMC)

- Use subsampling to decouple from dataset size
- Provide speed-ups, but at the cost of introducing bias

Metropolis-Hastings (M-H) correction

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- Are a family of sampling methods popular in Bayesian inference
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Stochastic gradient MCMC (SG-MCMC)

- Use subsampling to decouple from dataset size
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Metropolis-Hastings (M-H) correction

- Removes bias by rejecting fraction of Markov chain's transitions
- Reintroduces dependency on dataset size

Our contribution in a nutshell

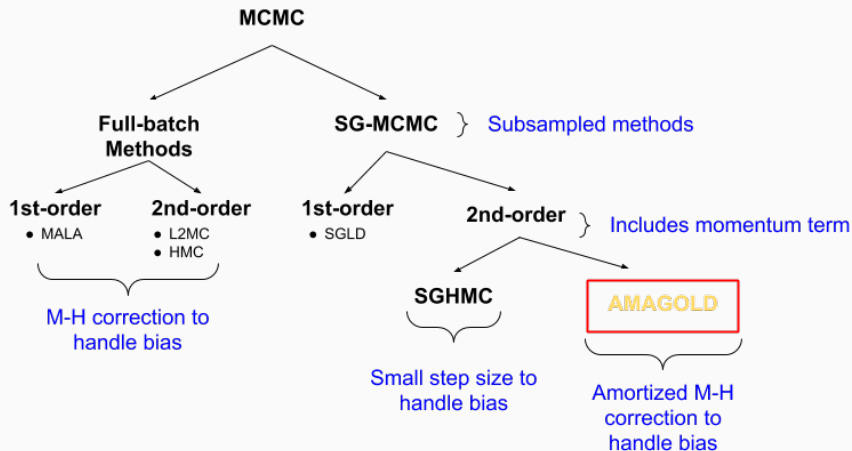
***Question:** Is there a way to construct an unbiased (i.e. exact) SG-MCMC algorithm that retains the efficiency we get from using stochastic gradients?*

***Answer:** Yes, which we demonstrate by introducing **AMAGOLD**:*

Exact without being prohibitively expensive

Uses M-H correction, amortizing its cost by applying it every T algorithm steps

Situating AMAGOLD within MCMC



Situating AMAGOLD within 2nd-order MCMC

Algorithm	Exact?	Stochastic Gradient?
AMAGOLD	Yes	Yes
L2MC	Yes	No
HMC	Yes	No
SGHMC	No	Yes

Given: Some dataset \mathcal{D} , domain Θ

Sample: From posterior distribution $\pi(\theta) \propto \exp(-U(\theta))$ where

$$U(\theta) = - \sum_{x \in \mathcal{D}} \log p(x|\theta) - \log p(\theta).$$

$U(\theta)$: Energy function

θ : Ranges over Θ

$\pi \propto \mu$: π is the unique distribution with PDF proportional to μ

A second-order chain (e.g. HMC, SGHMC, L2MC) *augments* state space with momentum r

Joint distribution:

$$\pi(\theta, r) \propto \exp(-H(\theta, r)) = \exp\left(-U(\theta) - \frac{1}{2\sigma^2}\|r\|^2\right),$$

H (Hamiltonian): measures total energy of system.

Full-batch energy function (e.g. HMC, L2MC)

$$U(\theta) = - \sum_{x \in \mathcal{D}} \log p(x|\theta) - \log p(\theta).$$

Need M-H correction step to prevent bias due to discretization

Stochastic gradient energy function (e.g. SGHMC, **AMAGOLD**)

$$\tilde{U}(\theta) \approx - \frac{|\mathcal{D}|}{|\tilde{\mathcal{D}}|} \sum_{x \in \tilde{\mathcal{D}}} \log p(x|\theta) - \log p(\theta).$$

Naively using stochastic gradient estimate can lead to convergence to wrong stationary distribution

Algorithm 1 SGHMC

- 1: **given:** Energy U , initial state $\theta \in \Theta$, step size ϵ , momentum variance σ^2 , friction β
 - 2: **loop**
 - 3: **optionally, resample momentum:**
 - 4: $r \sim \mathcal{N}(0, \sigma^2)$
 - 5: **initialize position and momentum:**
 - 6: $r_{\frac{1}{2}} \leftarrow r, \theta_0 \leftarrow \theta$
 - 7: **for** $t = 1$ **to** T **do**
 - 8: **position update:** $\theta_t \leftarrow \theta_{t-1} + \epsilon \sigma^{-2} r_{t-\frac{1}{2}}$
 - 9: **sample noise** $\eta_t \sim \mathcal{N}(0, 4\epsilon\beta\sigma^2)$
 - 10: **sample random energy component** \tilde{U}_t
 - 11: **update momentum:**
$$r_{t+\frac{1}{2}} \leftarrow r_{t-\frac{1}{2}} - \epsilon \nabla \tilde{U}_t(\theta_t) - 2\epsilon\beta r_{t-\frac{1}{2}} + \eta_t$$
 - 12: **end for**
 - 13: **new values:** $(\theta, r) \leftarrow (\theta_T, r_{T+\frac{1}{2}})$
 - 14: \triangleright no M-H step
 - 15: **end loop**
-

Second-order MCMC

- Compute posterior distribution using sampling

- Include momentum term

- Full-batch variants (L2MC, HMC) and minibatch

- Minibatch variants (SGHMC, **AMAGOLD**)

Exact methods

- Guarantee convergence to correct stationary distribution (L2MC, HMC, **AMAGOLD**)

- Use M-H correction to remove bias

Inexact methods

- Do not have same convergence guarantees (SGHMC)

Detailed Balance Condition A Markov chain with transition probability operator G is reversible if for any pair of states x and y

$$\pi(x)G(x, y) = \pi(y)G(y, x).$$

Computing the M-H acceptance probability

$$\tau = \min \left(1, \frac{\pi(y)P(y, x)}{\pi(x)P(x, y)} \right).$$

Given some measure-preserving involution over the state space denoted $x \mapsto x^\perp$, a chain G is *skew-reversible* if $\pi(x) = \pi(x^\perp)$ and

$$\pi(x)G(x, y) = \pi(y^\perp)G(y^\perp, x^\perp).$$

For Hamiltonian dynamics we use the involution that negates the momentum, i.e. $(\theta, r)^\perp = (\theta, -r)$.

AMAGOLD: Amortized Metropolis-Adjusted stochastic Gradient second-Order Langevin Dynamics

Convergence rate intuition:

Essentially equivalent to full-batch L2MC, up to a constant factor
Approaches L2MC's rate as batch size increases or step size decreases

AMAGOLD's relationship to prior methods

Algorithm	Exact?	Stochastic Gradient?
AMAGOLD	Yes	Yes
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HMC	Yes	No
SGHMC	No	Yes

Full-batch

→ L2MC with AMA

Full-batch, $\beta = 0$, resample

→ HMC

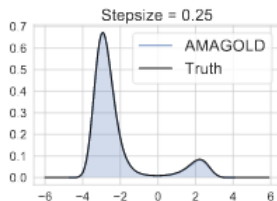
Disable M-H, adjust
hyperparameters

→ SGHMC

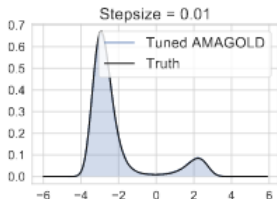
AMAGOLD in practice



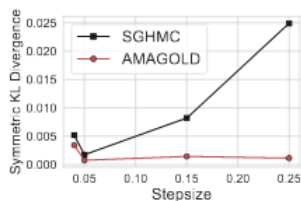
(a) SGHMC



(b) AMAGOLD

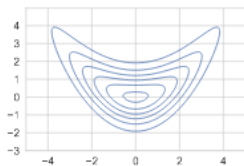


(c) Tuned AMAGOLD

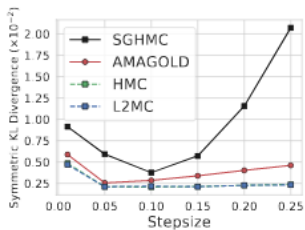


(d) KL Divergence

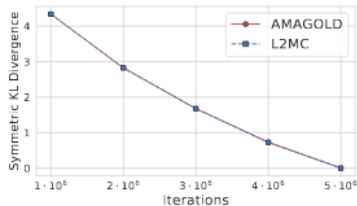
AMAGOLD on synthetic data



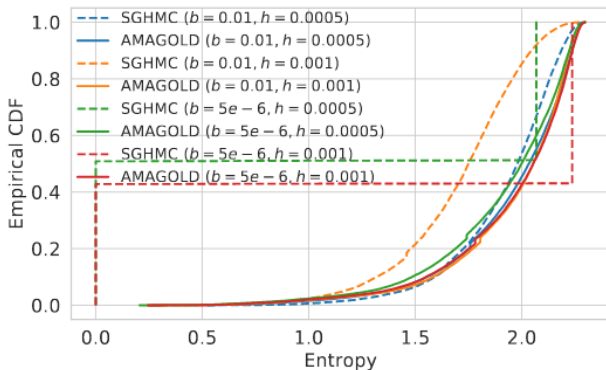
(a) Dist1



(b) KL comparison on Dist1



AMAGOLD on large-scale BNNs



Summary and future work

